

Thesis Outline

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1 Introduction

Opening Notes

- ◆ Medical imaging, particularly in the context of registration
- ◆ Analysis of images in the studies of a group: structural change, inter- and intra-subject, etc.
- ◆ The *need* to compare images

Non-Rigid Registration (NRR)

- ◆ The Purpose of Registration
- ◆ Alignment of images
- ◆ Subsequent analysis of change
- ◆ Performing comparisons; task simplified owing to NRR

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Models

- ◆ Identification of corresponding points across image sets
- ◆ Alignment of corresponding point using non-rigid registration
- ◆ Comparison independent of pose variations (thus a like-with-like comparison)
- ◆ Models embody 'knowledge' about structures of interest
- ◆ Explanation of the variation using decomposition, which is inherent in the models

The Tie Between NRR and Models

- ◆ Registration infers a particular dense (pixel-to-pixel/voxel-to-voxel) correspondence
- ◆ Models require correspondence to be built
- ◆ Good models benefit from good NRR
- ◆ Registration can be build models by producing correspondences

Optimal Shapes and Assessment of Shape Models

- ◆ An idea that was put to practice before (successfully so)
- ◆ Find corresponding points that define contours (outline of constituent structures in ROI). This is not yet automated.
- ◆ Identify points of interest, e.g. edges
- ◆ Describe shape by applying principal component analysis to points distribution
- ◆ Define descriptor of shape model's 'quality', based on key attributes
- ◆ Identify optimal models, use an objective function to accommodate and use figures of merit

Aims Of the Project

- ◆ Extend work on shape, generalise it to account for and incorporate intensity information
- ◆ Obviate the need to segment structures, make the model-build framework automatic
- ◆ Combine NRR and models to form a joint framework

- ◆ This involves assessment of appearance model (shape and intensity), as well as use of an objective function builds good models
- ◆ Assess NRR

Extending the Existing Framework (Shape ▷ Appearance)

Assessment of Registration

Cover work that is contained in the heart of the thesis (a gist)

- ◆ Benchmark existing registration methods (problem perceived 'in reverse')
- ◆ Build models automatically
- ◆ Data-driven analysis
 - ▷ Models without human intervention
 - ▷ Registration assessment without annotation

Contributions

- ◆ Rapid evaluation of registrations, without need for ground truth
- ◆ Reason about quality of different NRR algorithms
- ◆ Build models automatically
- ◆ Evaluate models
- ◆ Complete framework for automatic or semi-automatic analysis of data

Thesis Organisation

2 Non-rigid Registration

- ◆ Registration involves warping and similarity measures

2.1 Image Warping

- ◆ Rigid, affine, and non-rigid transformations
- ◆ Methods (splines, diffeomorphic warps and functions, deformation fields, etc.)

2.2 Similarity Measures

Introduction

- ◆ Purpose
- ◆ General technical details

Methods

- ◆ MSD/SSD
- ◆ Correlation ratio
- ◆ Mutual information
- ◆ Model-based (to be described later, among newly-developed methods)

2.3 Group-wise versus Pair-wise

(Possibly omitted, depending if space permits)

- ◆ Introduction: the distinction between the two
- ◆ Discussion: Flaws associated with pair-wise NRR
- ◆ Examples/results
- ◆ Previous work on group-wise registration

2.4 Existing NRR Assessment Methods

- ◆ Presenting the main methods in current use
- ◆ Elaborate on generalised overlap-based assessment - Tanimoto and Dice (the latter in brevity)

3 Models

3.1 Statistical Models

Introduction

- ◆ Method for describing variation in data

Rationale

- ◆ Image analysis
- ◆ Synthesis (which includes extrapolation from the given data), fitting to data
- ◆ Thesis introduces an important new application of models

3.2 Shape Models

Deformable Models

- ◆ The principles
- ◆ Bending energy
- ◆ Practical example/s

Correspondence

- ◆ The need for corresponding points
- ◆ Vectorisation and embedment in space

Principal Component Analysis

- ◆ The principles of the method
- ◆ Mathematics involved
- ◆ Issues and weaknesses (e.g. banana-shaped distributions and linearity of the models, which are later introduced in a technical context)

Model Construction

- ◆ More elaborate discussion, in relation to PCA
- ◆ Equations to follow

Shape Models

- ◆ Learning how shapes vary in a set
- ◆ Construction process, including equations, alignment to CoG
- ◆ Visualisation of the models in practical use

3.3 Appearance Models

Intensity Models

- ◆ Introduction of the second type of variation, which is 'texture'.
- ◆ Construction using normalisation, warping to mean, raster scan, etc.
- ◆ Visualisation of the concept

Combined Models

- ◆ Formulation that involves and brings together the above, examples included

3.4 Active Models and Fitting

- ◆ Matching using the notion of *synthesis*
- ◆ Discrepancy as a deficiency, which later comes into play
- ◆ Computing distance from a match/fit to an unseen image (relating to shuffle distance, to be discussed later)

4 MDL Shape Models

4.1 Shapes and Correspondence

- ◆ Returning to the issue of point correspondence
- ◆ Exemplifying models where correspondences are poor

4.2 Learning Shapes

- ◆ Principled approach

4.3 Objective Function and Optimisation

- ◆ Variety of functions
- ◆ Optimising correspondences
- ◆ Objective function
- ◆ Determinant-based optimisation
- ◆ Minimum description length
- ◆ Numerical results from past work
- ◆ More results and illustrations (visual)

5 Model-Based Registration

5.1 Model-based Registration

- ◆ Initial Experiments to demonstrate feasibility
- ◆ Data - description, images
- ◆ Clamped-plate spline-based warps
- ◆ Determinant-based objective function
- ◆ MDL objective function

- ◆ Experiments
- ◆ Results

5.2 Model Building

- ◆ Introduction and validation (before next chapter on evaluation begin)
- ◆ Models built from 1-D model-based registration
- ◆ Personal contribution to full implementation in 2- and 3-D
- ◆ Examples of 2-D models

6 Assessment of Models and Non-Rigid Registration

Generalisation and Specificity

- ◆ Applied to images (extension of work on shapes)
- ◆ Synthesis, clouds in hyperspace
- ◆ Need image distances to be measured

Image distance measures

- ◆ Euclidean distance
- ◆ Use of the shuffle distance
- ◆ Nearest match to identical pixel intensity (Wang)
- ◆ Efficient implementation and *ad hoc* optimisations

Normalisation

- ◆ Entropy

7 Validation Methodology and Experiments

- ◆ Controlled perturbation
- ◆ Definition of sensitivity
- ◆ Comparison with overlap

8 Application to Non-Rigid Registration Evaluation

- ◆ Groupwise vs. pairwise discussion
- ◆ Experiments involving different NRR algorithms and quantitative comparison

9 Extensions to 3-D

3-D Extension of the Method

10 Future Exploration

10.1 Pitfalls

- ◆ Long time to synthesise many images and compute distances
- ◆ Computation of Sensitivity and Generalisation not principled, corrected by pseudo-entropy of graphs

10.2 Extending the Scheme

- ◆ Normalisation
- ◆ Improving the range of displacements where results can be differentiated
- ◆ Improving sensitivity further

11 Conclusions

Summary, discussion, contributions and conclusions

- ◆ Building models without human intervention
- ◆ Developed a model-based objective function
- ◆ Model evaluation scheme
- ◆ Registration evaluation scheme
- ◆ Group-wise registration better than pair-wise

12 Appendices

- ◆ Perturbation
- ◆ Formulation of error bar calculations
- ◆ Objective function for model-based registration
- ◆ ...